

Mathematics, Pusan National University

# LINEAR ALGEBRA AND LEARNING FROM DATA

## Singular Values and Singular Vectors in the SVD

Taehyeong Kim  
th\_kim@pusan.ac.kr

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Review

1.8.10 The SVD for Derivatives and Integrals

Pseudoinverse

Least Square Problem

Pseudoinverse and Least Square Problem



## Review SVD

$A = U\Sigma V^T$  where  $U$  and  $V$  are square orthogonal matrices.



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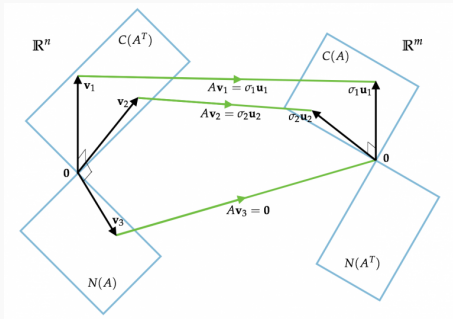


Figure: SVD and Big picture



$$A = U\Sigma V^T = \sigma_1 \mathbf{u}_1 \mathbf{v}_1^T + \sigma_2 \mathbf{u}_2 \mathbf{v}_2^T + \cdots + \sigma_r \mathbf{u}_r \mathbf{v}_r^T$$

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## Application of SVD : image compression



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The original image needs  $451 \times 439 = 197989$  pixel information, but the image can be compressed effectively through SVD. If we use only the singular values up to the 100th, we only need  $100 \times (451 + 439) = 89000$  values.



Historically, the first SVD was not for vectors but for **functions**.

### Example. Integral and Derivative

$$A\mathbf{x}(s) = \int_0^s \mathbf{x}(t)dt \text{ and } D\mathbf{x}(t) = \frac{d\mathbf{x}}{dt}$$



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$DA = I$  but  $AD \neq I$ ! (For example,  $f(x) = x + 1$ )

$D$  is the **pseudoinverse of**  $A$  denoted as  $A^+$ .



We can get pseudoinverse by SVD.

$$\begin{aligned} A^+ &= (U\Sigma V^T)^+ \\ &= V\Sigma^+ U^T \\ &= \underbrace{\begin{bmatrix} \mathbf{v}_1 & \cdots & \mathbf{v}_r & \cdots & \mathbf{v}_n \end{bmatrix}}_{n \times n} \underbrace{\begin{bmatrix} 1/\sigma_1 & & & & \\ & \ddots & & & \\ & & 1/\sigma_r & & \end{bmatrix}}_{n \times m} \underbrace{\begin{bmatrix} \mathbf{u}_1 & \cdots & \mathbf{u}_r & \cdots & \mathbf{u}_m \end{bmatrix}^T}_{m \times m} \\ &\Rightarrow A^+ A = (V\Sigma^+ U^T)(U\Sigma V^T) = I \end{aligned}$$



Let  $A$  is full-column rank matrix, if there is no solution of the matrix equation  $A\mathbf{x} = \mathbf{b}$ , we can find the best solution  $\mathbf{x}^+$  such that  $A\mathbf{x}^+ = \mathbf{p}$ . For example,

$$A\mathbf{x} = \begin{bmatrix} 1 & 1 \\ 2 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = \mathbf{b} \quad (1)$$



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(1) doesn't have solution, multiply both sides by  $A^T$  and project  $b$  into the column space of  $A$ .

$$A^T A\mathbf{x}^+ = \begin{bmatrix} 14 & 6 \\ 6 & 3 \end{bmatrix} \begin{bmatrix} \hat{x}_1 \\ \hat{x}_2 \end{bmatrix} = \begin{bmatrix} 11 \\ 5 \end{bmatrix} = A^T \mathbf{b} \Rightarrow \mathbf{x}^+ = \begin{bmatrix} 1/2 \\ 2/3 \end{bmatrix} \quad (2)$$

$$\Rightarrow A\mathbf{x}^+ = \mathbf{p} = \begin{bmatrix} 7/6 \\ 5/3 \\ 13/6 \end{bmatrix}, \mathbf{e} = \begin{bmatrix} -1/6 \\ 1/3 \\ -1/6 \end{bmatrix}$$

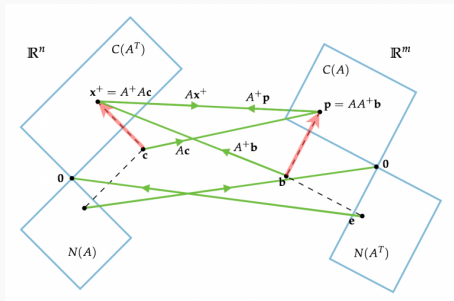


Figure: Pseudoinverse and Big picture

If we apply the pseudo inverse matrix, the solution is  $\mathbf{x}^+ = A^+\mathbf{b}$  even if  $A$  is not full rank.





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Calculate pseudoinverse of  $A$ ,

$$A^+ = \begin{bmatrix} -1/2 & 0 & -1/2 \\ -1/6 & 1/3 & 5/6 \end{bmatrix}$$

$$\Rightarrow \mathbf{x}^+ = A^+\mathbf{b} = \begin{bmatrix} -1/2 & 0 & -1/2 \\ -1/6 & 1/3 & 5/6 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 1/2 \\ 2/3 \end{bmatrix}$$



Thank you!